

Shantilal Shah Engineering College, Bhavnagar

Sem-II (All Branches)

Sub : Vector Calculus & Linear Algebra (2110015)

Tutorial : 1

Topic : Matrices and Linear Equations (Ex-1 to 14)

Ex-1 In each part determine whether the following matrix is in row echelon form, reduced row echelon form, both or neither :

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & -6 & 4 & 3 \\ 0 & 1 & 3 & 2 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & -1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 0 & 1 & 2 \\ 0 & 1 & 0 & 7 \end{bmatrix}, \begin{bmatrix} 0 & 1 & -4 & 0 & 1 \\ 0 & 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Ex-2 Find the a row echelon form (Gauss-elimination method) of the following Matrices & find it's rank also:

$$\begin{bmatrix} 0 & -1 & 2 & 3 \\ 2 & 3 & 4 & 5 \\ 1 & 3 & -1 & 2 \\ 3 & 2 & 4 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2 & -3 & 1 \\ -1 & 0 & 3 & 4 \\ 0 & 1 & 2 & -1 \\ 2 & 3 & 0 & -3 \end{bmatrix}, \begin{bmatrix} 3 & 1 & -1 & 2 \\ 1 & -1 & 1 & 2 \\ 2 & 2 & 1 & 6 \end{bmatrix}, \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

Ex-3 Find the a reduced row echelon form (Gauss Jordan -elimination method) of the following Matrices& find it's rank also:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}, \begin{bmatrix} 1 & 2 & -3 & 1 \\ -1 & 0 & 3 & 4 \\ 0 & 1 & 2 & -1 \\ 2 & 3 & 0 & -3 \end{bmatrix}, \begin{bmatrix} 3 & 1 & -1 & 2 \\ 1 & -1 & 1 & 2 \\ 2 & 2 & 1 & 6 \end{bmatrix}, \begin{bmatrix} 1 & -1 & 1 & 0 & 2 \\ 2 & -2 & 0 & 2 & 2 \\ -1 & 1 & 2 & -3 & 1 \\ -2 & 2 & 1 & -3 & -1 \end{bmatrix}$$

Ex-4 Solve each of the following system by Gauss elimination method:

- (i) $x + y + z = 9, x + y - z = 1, 2x + 2y - 2z = 0.$
- (ii) $3x + y - 3z = 13, 2x - 3y + 7z = 5, 2x + 19y - 47z = 32.$
- (iii) $-x + 3y + 4z = 30, 3x + 2y - z = 9, 2x - y + 2z = 10.$
- (iv) $-a + 3b - 4c = 3, 3a + 2b - c = 8, 2a - b + 2c = 1.$

Ex-5 Investigate for what value of λ and η the equations

$$x + 2y + z = 8, 2x + 2y + 2z = 13, 3x + 4y + \lambda z = \eta.$$

Have (i) no solution (ii) unique Solution (iii) many solution.

Ex-6 Find the number of parameters in general solution of $Ax=0$ if A is 5x7 Matrix of rank 3.

EX-7 If A is an mxn matrix, what is the largest possible value for it's rank ?.

Ex-8 Examine the consistency of the following system of equations & solve them, If they are consistent.

- (i) $x + 4y + 4z = 2, 2x + 4y + z = 1, x + 5y + 2z = -1, x + 2y + 8z = 8.$
- (ii) $x - 2y + z - 3w = -3, -3x + y - z + 2w = 2, 4x + 3y - 3z + w = 1.$
- (iii) $5x + 3y + 4z = 0, 2x - y + z = 0, 3x + y + 2z = 0.$
- (iv) $3x + 4y - z = 5, x + y - z = 4, 3x - 4y + z = 3.$

Ex-9 Solve the following system equation by Gauss Jordan-elimination method:

- (i) $x + 2y + z = 3, 2x + y + 3z = 5, 2x + 4y + 2z = 7.$
- (ii) $2x + y - z = 2, x - 3y + z = 1.$

Ex-10 Find the inverse of following matrices by Gauss Jordan method:

$$(i) \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & -1 \\ 0 & 1 & 0 \end{bmatrix}, (ii) \begin{bmatrix} \frac{1}{5} & \frac{1}{5} & \frac{-2}{5} \\ \frac{1}{5} & \frac{1}{5} & \frac{1}{10} \\ \frac{1}{5} & \frac{-4}{5} & \frac{1}{10} \end{bmatrix}, (iii) \begin{bmatrix} 3 & -1 & 5 \\ 2 & 6 & 4 \\ 5 & 5 & 9 \end{bmatrix}, (iv) \begin{bmatrix} -1 & 2 & 3 \\ -4 & 5 & -6 \\ 7 & -8 & 9 \end{bmatrix}$$

Ex-11 Find the rank of the matrix A in terms of determinant, where $A = \begin{bmatrix} 2 & -1 & 3 \\ 4 & -2 & 6 \\ -6 & 3 & -8 \end{bmatrix}$

Ex-12 Define the following:

Rank of matrix, Singular matrix, Invertible matrix, Symmetric matrix.

EX-13 Use Cramer's rule to find the solution of the system

- (1) $x + 2y + z = 3, 2x + y + 3z = 5, 2x + 4y + 2z = 7$
- (2) $x - 4y + z = 6, 4x - y + 2z = -1, 2x + 2y - 3z = -20$

EX-14 Find the rank of the given matrix by reducing it to normal form.

$$\begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 3 \\ 0 & -1 & 3 \end{bmatrix}, \begin{bmatrix} 1 & 4 & 5 & 2 \\ 2 & 1 & 3 & 0 \\ -1 & 3 & 2 & 2 \end{bmatrix}$$

Shantilal Shah Engineering College, Bhavnagar

Sem-II (All Branches)

Sub : Vector Calculus & Linear Algebra (2110015)

Tutorial :2

Topic : Vector in R^n , V.Space, Subspace & basis (Ex-1 to 16)

Ex-1 Find a vector in R^2 with Euclidean norm zero, and whose inner product with $(-3, 1)$ is zero.

Ex-2 State and prove Schwartz inequality and triangle inequality.

Verify it for the following vectors.

(1) $u = (0, -2, 2, 1)$ & $v = (-1, -1, 1, 1)$.

(2) $u = (0, -2, 2)$ & $v = (-1, -1, 1)$.

(3) $u = (0, 2, 2, 1)$ & $v = (1, -1, 1, 1)$.

(4) $u = (0, -2, 2, 5)$ & $v = (-1, -1, 1, 0)$.

(5) $u = (0, -2, 2, 1, -2)$ & $v = (-1, -1, 1, 1, 2)$.

Ex-3 State and prove Pythagorean theorem

show that $u = (3, 0, 1, 0, 4, -1)$ & $v = (-2, 5, 0, -3, -18)$ are orthogonal and verify Pythagorean theorem hold.

Ex-4 Find the value of k for $u = (k, k, 1)$ & $v = (k, 4, 3)$ if u & v are orthogonal.

Ex-5 Prove that $uv = \frac{1}{4}\|u+v\|^2 - \frac{1}{4}\|u-v\|^2$. where $u, v \in R^n$.

Ex-6 Show that the set of polynomials (degree at most n) with real coefficients is vector space

Ex-7 Show that set of all 2×2 matrices of the form $\begin{bmatrix} a & l \\ l & b \end{bmatrix}$ with

addition define by $\begin{bmatrix} a & l \\ l & b \end{bmatrix} + \begin{bmatrix} c & l \\ l & d \end{bmatrix} = \begin{bmatrix} a+c & l \\ l & b+d \end{bmatrix}$ and

scalar multiplication $k \begin{bmatrix} a & l \\ l & b \end{bmatrix} = \begin{bmatrix} ka & l \\ l & kb \end{bmatrix}$ is a vector space,

where all the entries are from R .

Ex-8 Check whether $V = R^n$ is a vector space with respect to the operation $(u_1, u_2) + (v_1, v_2) = (u_1 + v_1 - 2, u_2 + v_2 - 3)$ &

$$\alpha(u_1, u_2) = (\alpha u_1 + 2\alpha - 2, \alpha u_2 - 3\alpha + 3) .$$

Ex-9 Show that $V \in R^n$ with the standard vector addition and scalar multiplication define as $\alpha(u_1, u_2) = (u_1, \alpha u_2)$ is not a vector space.

Ex-10 Show that W is a subspace of P_3 , the set of all polynomials of degree 3 or less.

Ex-11 Which of the following are subspace of some Euclidian space.

(a) $S = \{(a+b, 3a-b, 2a+b) / a, b \in R\}$

(b) $S = \{(x, y) / x = 3y\}$

(c) $S = \{(x, y, z) / x + y - z = 0, 4x - 2y + z = 2\}$

(d) $S = \{(x, y) / xy \geq 0\}$

(e) $S = \{(x, y, z) \in R^3 / x^2 + y^2 + z^2 = 1\}$

(f) $S = \{A_{n \times n} / Ax = 0 \Rightarrow x = 0\}$.

(g) $S = \{X \in M_{n \times n} / X^T = -X\}$

(h) $S = \{X \in M_{n \times n} / X^T X = I\}$

Ex-12. Determine the following polynomials span of P_2 :

$$p_1 = 1 - x + 2x^2, p_2 = 5 - x + 4x^2, p_3 = -2 - 2x + 2x^2.$$

Ex-13 Determine whether $v_1 = (1, 1, 2), v_2 = (1, 0, 1)$ & $v_3 = (2, 1, 3)$

Span the vector space R^3 .

Ex-14 Show that the set $S = \{e^x, xe^x, x^2e^x\}$ in $C^2(-\infty, \infty)$ is linearly independent.

EX-15 Show that $S = \left\{ \begin{bmatrix} 1 & 2 \\ 1 & -2 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 2 \\ 3 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ -1 & 2 \end{bmatrix} \right\}$ is a basis

for M_{22}

Ex-16 Find the standard basis vector that can be added to the set

$$s = \{(1, 0, 3), (2, 1, 4)\}$$
 to produce a basis for R^3 .

Ex-16 Show that the set $s = \{(1, 2), (3, -1), (1, 0)\}$ is not basis for R^2 .

Ex-1 Define Inner Product Space and Determine which of the following are inner Product on R^3 if $u=(u_1, u_2, u_3), v=(v_1, v_2, v_3)$,

- (i) $\langle u, v \rangle = 2u_1v_1 + u_2v_2 + 4u_3v_3$,
(ii) $\langle u, v \rangle = u_1^2v_1^2 + u_2^2v_2^2 + u_3^2v_3^2$.

Ex-2 If $u = (u_1, u_2), v = (v_1, v_2)$ are vectors in R^2 then prove that R^2 is an inner product space with respect to the inner product defined as $\langle u, v \rangle = 4u_1v_1 + u_2v_1 + 4u_1v_2 + 4u_2v_2$.

Ex-3 Show that $\langle u, v \rangle = 9u_1v_1 + 4u_2v_2$ is the inner product on R^2 generated by the matrix $A = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$.

Ex-4 Let $u = (u_1, u_2), v = (v_1, v_2)$. find a matrix that generates the following inner products.

- (i) $\langle u, v \rangle = 3u_1v_1 + 5u_2v_2$, (ii) $\langle u, v \rangle = 4u_1v_1 + 6u_2v_2$.

Ex-5 Let R^3 have the Euclidean inner product. Use Gram-Schmidt Process to transform the basis vectors $u_1 = (1,0,0), u_2 = (3,7,-2), u_3 = (0,4,1)$ into an orthonormal basis.(IMP)

Ex-6 Use Gram-Schmidt process to transform the basis $\{1, x, x^2\}$ of P_2 into an orthonormal basis

- If (a) $\langle p, q \rangle = p(0)q(0) + p(1)q(1) + p(2)q(2)$,
(b) $\langle p, q \rangle = \int_0^2 p(x)q(x)dx$.(IMP)

Ex-7 Find a basis for the orthogonal complement of the subspace W of the corresponding space R^n spanned by the vectors (i) $u_1=(2,0,-1)$ (ii) $u_2=(4,0,-2)$ in R^3 .

Ex-8 Use Gram-Schmidt process to transform the basis $\left\{ \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ of M_{22} into an orthogonal basis if $\langle A, B \rangle = tr(AB^T)$.

Ex-9 Find the Least squares solution of the system $Ax=b$ given by $x_1 + x_2 = 7, -x_1 + x_2 = 0, -x_1 + 2x_2 = -7$.

Ex-10 Find the Least squares solution of the system $Ax=B$ given by $x_1 - x_2 = 4, 3x_1 + 2x_2 = 1, -2x_1 + 4x_2 = 3$.

Ex-11 Let the vector space P_2 have the inner product

$$\langle p, q \rangle = \int_{-1}^1 p(x)q(x)dx$$

- (i) Find $\|p\|$ for $p = x^2$, (ii) Find $d(p, q)$ if $p = 1$ & $q = x$.

Ex-12 For $U = \begin{bmatrix} u_1 & u_2 \\ u_3 & u_4 \end{bmatrix}$ & $V = \begin{bmatrix} v_1 & v_2 \\ v_3 & v_4 \end{bmatrix}$ in M_{22} , define

$\langle U, V \rangle = u_1v_1 + u_2v_2 + u_3v_3 + u_4v_4$ for the matrices A & B , verify Cauchy-Schwartz inequality and find the cosine of the angle between

them, if $A = \begin{bmatrix} 2 & 6 \\ 1 & -3 \end{bmatrix}$ & $B = \begin{bmatrix} 3 & 2 \\ 1 & 0 \end{bmatrix}$.

Ex-1 Determine whether the following functions are linear transformations:

- (i) $T: M_{mn} \rightarrow M_{nm}$, where $T(A) = A^T$.
- (ii) $T: M_{nn} \rightarrow R$, where $T(A) = \det(A)$.
- (iii) $T: M_{nn} \rightarrow R$, where $T(A) = \text{tr}(A)$.

Ex-2 Consider the basis $S=\{v_1, v_2\}$ for R^2 , where $v_1=(1,1)$ and $v_2=(1,0)$

and let $T: R^2 \rightarrow R^2$ be the linear transformation such that

$$T(v_1) = (1, -2) \text{ and } T(v_2) = (-4, 1).$$

Find a formula for $T(x_1, x_2)$ and use the formula to find $T(5, -3)$.

Ex-3 Let $T_1: P_2 \rightarrow P_2$ and $T_2: P_2 \rightarrow P_2$ be the linear transformation given

$$\text{by } T_1(p(x)) = p(x+1) \text{ and } T_2(p(x)) = xp(x).$$

Find $(T_2 \circ T_1)(a_0 + a_1x + a_2x^2)$.

Ex-4 Let $T: P_2 \rightarrow R^2$ be the linear transformation define by

$$T(a_0 + a_1x + a_2x^2) = (a_0 - a_1, a_1 + a_2) \text{ the}$$

(I) Find a basis for $\ker(T)$,

(II) Find a basis for $R(T)$,

(III) Verify the dimension theorem.

Ex-5 In each case, Determine whether the linear transformation is

one to one, onto, or both, or neither

(I) $T: R^2 \rightarrow R^2$ where $T(x_1, x_2) = (x_1 + x_2, x_1 - x_2)$.

(II) $T: R^3 \rightarrow R^3$ where $T(x_1, x_2, x_3) = (x_1 + 3x_2, x_2, x_3 + 2x_1)$.

Ex-6 Let $T: R^3 \rightarrow R^3$ be the linear operator define by the formula

$$T(x_1, x_2, x_3) = (x_1 - x_2 + x_3, 2x_2 - x_3, 3x_2 + 2x_1),$$

Determine whether T is one to one. If So, find $T^{-1}(x_1, x_2, x_3)$.

Ex-7 Find the rank and nullity of transformation $T: R^3 \rightarrow R^2$,

$$T(x, y, z) = (x + y + z, x + y).$$

Ex-8 Let $T: R^2 \rightarrow R^3$ be the linear transformation define

$$\text{by } T \left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} x_2 \\ -5x_1 + 13x_2 \\ -7x_1 + 16x_2 \end{bmatrix},$$

Find the matrix of the transformation T w.r.t. the bases

$S_1 = \{v_1, v_2\}$ for R^2 and $S_2 = \{w_1, w_2, w_3\}$ for R^3 ,

$$\text{where } v_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 5 \\ 2 \end{bmatrix}, w_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, w_2 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}, w_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}.$$

Ex-9 Find the associate matrix of the linear transformation $T: R^3 \rightarrow R^3$,

$$T(u_1, u_2, u_3) = (u_1 + u_2, u_2 + u_3, u_1 + u_3) \text{ with}$$

$$B = \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\} \text{ \& } B' = \{(1, 0, 1), (0, 1, 0), (1, 0, -1)\}$$

for the domain and co-domain of T respectively.

Ex-10 If $T: P_2 \rightarrow P_3$ be the linear transformation define

$$\text{by } T(p(x)) = xp(x+1), \text{ then find the matrix } [T]_{B', B}$$

w.r.t bases $B = \{1, x, x^2\}$ \& $B' = \{1, x, x^2, x^3\}$.

Ex-11 Let $T: R^2 \rightarrow R^3$ be the linear transformation define

$$\text{by } T \left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} x_2 \\ -5x_1 + 13x_2 \\ -7x_1 + 16x_2 \end{bmatrix}$$

, find the matrix for the transformation T w.r.t the bases

$B = \{u_1, u_2\}$ \& $B' = \{v_1, v_2, v_3\}$ for R^2 and R^3 respt. Where

$$u_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} 5 \\ 2 \end{bmatrix}, v_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, v_2 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}.$$

Ex-12 Using induced matrix associated with each transformation determine

the new point after applying the transformation to the given point,

(a) $x=(1, -2, 1)$ reflected about xz-plane.

(b) $x=(9, 4, -2)$ projected on the x-axis.

(c) $x=(1, -3,)$ rotated 30° in the counter clock wise direction.

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Sem-II (All Branches)

Sub : Vector Calculus & Linear Algebra (2110015)

Tutorial :5

Topic : Vector Calculus (Ex-1 to 18)

Ex-1 Find the Gradient $f(x, y, z) = 2z^3 - 3(x^2 + y^2)z + \tan^{-1}(xz)$ at (1,1,1).

Ex-2 If $r = x\hat{i} + y\hat{j} + z\hat{k}$, evaluate

$$(a)\nabla r^n, (b)\nabla|r^3|, (c)\nabla r, (d)\nabla(\ln r), (e)\nabla\left(\frac{1}{r}\right).$$

Ex-3 Find the angle between the surfaces $x^2 + y^2 + z^2 = 9$, and $z = x^2 + y^2 - 3$ at the Point (2,-1,2)

Ex-4 Find the derivative of $f(x, y) = x^2 \sin 2y$ at the point $\left(1, \frac{\pi}{2}\right)$ in the direction of $v = 3\hat{i} - 4\hat{j}$.

Ex-5 Find the directional derivative of the function $f(x + y) = ax + by$; a,b are constants, at the point (0,0) which makes an angle of 30° with positive x-axis.

Ex-6 The temperature at any point in space is given by $T = xy + yz + zx$. Determine the derivative of the vector $3\hat{i} - 4\hat{k}$ at the point (1, 1, 1).

Ex-7 Find the potential function for the field $F = e^{y+2z}(\hat{i} + x\hat{j} + 2x\hat{k})$.

Ex-8 Prove that $r''r$ is irrotational.

Ex-9 Find the directional derivative of $\text{div } F$ at (2,2,1) in the direction of normal to the sphere $x^2 + y^2 + z^2 = 9$, where $F = x^2z\hat{i} + xy^2\hat{j} + yz^2\hat{k}$.

Ex-10 Prove that $\nabla^2 f(r) = f''(r) + (2/r)f'(r)$.

Ex-11 Find the parametric equations of the line joining (-3,2) and (2,-1).

Ex-12 Integrate $f(x, y, z) = x + \sqrt{y} - z^2$ over the path $c = c_1 \cup c_2$ from (0,0,0) to (1,1,1) with $c_1 : r(t) = t\hat{i} + t^2\hat{j}$, $c_2 : r(t) = \hat{i} + \hat{j} + t\hat{k}$, $0 \leq t \leq 1$.

Ex-13 Show that

$$\vec{F} = (y^2 - z^2 + 3yz - 2x)\hat{i} + (3xz + 2xy)\hat{j} + (3xy - 2xz + 2z)\hat{k}$$

is both solenoid and irrotational.(IMP)

Ex-14 Find the value of n for which the vector $r^n \vec{r}$ is solenoidal, where $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$.

Ex-15 Show that $\vec{E} = \frac{\vec{r}}{r^2}$ is irrotational.

Ex-16 State Green's Theorem. Verify it for

$$\oint_C [(x^2 - 2xy)dx + (x^2y + 3)dy],$$

where C is Boundary of the region bounded by the parabola $y = x^2$ and $y = x$.

Ex-17 Evaluate $\oint_C [(x^2 - \cosh y)dx + (y + \sin x)dy]$ by Greens theorem, where C is the rectangle with vertices (0,0), $(\pi, 0)$, $(\pi, 1)$, (0,1).

Ex-18 State only Stokes and Gauss-Divergence theorem.

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Sem-II (All Branches)

Sub : Vector Calculus & Linear Algebra (2110015)

Tutorial :6

Topic : Eigen values & Eigen vectors (Ex-1 to 18)

Ex-1 Find the Eigen value and Eigen Vector for the following matrices:

$$(1) \begin{bmatrix} 5 & 3 \\ 1 & 3 \end{bmatrix} (2) \begin{bmatrix} 3 & 2 & 3 \\ 0 & 6 & 10 \\ 0 & 0 & 2 \end{bmatrix} (3) \begin{bmatrix} 1 & -6 & -4 \\ 0 & 4 & 2 \\ 0 & -6 & -3 \end{bmatrix} (4) \begin{bmatrix} -420 & \frac{1}{2} & 576 \\ 0 & 0 & 0.6 \\ 0 & 0 & \sqrt{3} \end{bmatrix}$$

Ex-2 Show that if $0 < \theta < \pi$, then $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ has no real Eigen Value and Consequently no Eigen Vectors.

Ex-3 For the matrix $A = \begin{bmatrix} 2 & 0 \\ 3 & 3 \end{bmatrix}$, Find the Eigen Values of

(i) A (ii) A^{-1} (iii) A^2 (iv) A^{-1} (v) $\text{adj}A$ (vi) $3A$ (vii) $A^3 + A^2 + A + 2I$.

Ex-4 Find the eigen values and bases for the eigenspaces of A^{25} and $A + 2I$, where $A = \begin{bmatrix} 3 & 0 \\ 8 & -1 \end{bmatrix}$

Ex-5 Define Algebraic and Geometric Multiplicity.

Determine the Algebraic and Geometric Multiplicity Of

$$(1) \begin{bmatrix} 3 & 0 \\ 8 & -1 \end{bmatrix}, (2) \begin{bmatrix} -2 & 2 & -3 \\ 2 & 1 & -6 \\ -1 & -2 & 0 \end{bmatrix}.$$

Ex-6 Find the eigenvalues and eigen vectors of the matrix A and discuss about its algebraic and geometric multiplicity,

$$\text{where } A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

Ex-7 Show that characteristic equation of a 2×2 matrix A can be expressed as $\lambda^2 - \text{tr}(A)\lambda + \det(A) = 0$.

Ex-8 State Caley-Hamilton theorem. Verify it for the following matrices

$$(1) \begin{bmatrix} 3 & 4 \\ 1 & 2 \end{bmatrix} (2) \begin{bmatrix} 1 & 1 & 2 \\ 3 & 1 & 1 \\ 2 & 3 & 1 \end{bmatrix}.$$

Ex-9 Using Caley-Hamilton theorem, find $A^2, A^{-1}, A^{-2}, A^{-3}$ if $A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$.

Ex-10 Using Caley-Hamilton theorem if $A = \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 2 \end{bmatrix}$, then prove that

$$A^8 - 5A^7 + 7A^6 - 3A^5 + A^4 - 5A^3 + 8A^2 - 2A + I = \begin{bmatrix} 8 & 5 & 5 \\ 0 & 3 & 0 \\ 5 & 5 & 8 \end{bmatrix}.$$

Ex-11 Find an Orthogonal matrix P that diagonalizes $A = \begin{bmatrix} 1 & 0 \\ -1 & 2 \end{bmatrix}$, and hence find A^{10} also find Eigen value of A^2 .

Ex-12 Find a matrix P that diagonalizes A and determine $P^{-1}AP$, where A is

$$(1) \begin{bmatrix} -1 & 4 & -2 \\ -3 & 4 & 0 \\ -3 & 1 & 3 \end{bmatrix}, (2) \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix},$$

Ex-13 Diagonalized orthogonally the matrices (i) $\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$ (ii) $\begin{bmatrix} 2 & 0 & 1 \\ 0 & 3 & 0 \\ 1 & 0 & 2 \end{bmatrix}$.

Ex-14 Show that $A = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$ is orthogonal.

Ex-15 Reduce the quadratic form

$$Q(x, y, z) = 3x^2 + 4xy + 3z^2 + 8xz + 8yz \text{ into canonical form.}$$

EX-16 Describe the conic whose equation is

$$5x^2 + 4xy + 8y^2 - 36 = 0.$$

Ex-17 Translate and rotate the coordinate axis, if necessary,

$$\text{to put the conic } 9x^2 - 4xy + 6y^2 - 10x - 20y = 5$$

in standard position. Find the equation of conic in equation of conic in the final coordinate system.

Ex-18 Find a change of variable that reduces the quadratic form

$$2x^2 + 2y^2 - 2xy \text{ to a sum of Squares and express the quadratic form in terms of new variables.}$$

